#### Information Percolation in Large Markets

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# Information Percolation

#### Markets

- Hayek (1945)
- Wolinsky (1990)
- Golosov, Lorenzoni, Tsyvinski (2008)

#### Social learning

- Banerjee and Fudenberg (1995)
- Acemoglu (2008)

# Setting

From Duffie and Manso (AER 2007):

► A continuum of agents matched pairwise independently to other agents at mean rate *r*.

► Payoff relevant states: 
$$X = \begin{cases} H & \text{with probability } \nu \\ L & \text{with probability } 1 - \nu \end{cases}$$

► Agent k is endowed with S<sub>k</sub> = {s<sub>1</sub>,..., s<sub>k<sub>n</sub></sub>}, {0, 1}-signals that are X-conditionally independent, with

$$P(s_i = 1 | X = H) \ge P(s_i = 1 | X = L).$$

- For almost every pair *j* and *k* of agents,  $S_j$  and  $S_k$  are disjoint.
- If j and k are matched, they share endowed and previously gathered signals.

#### Information is Additive in Types

For any conditional probability p ∈ (0, 1) of the event {X = H}, we define the associated information type

$$\Theta(p) = \log \frac{(1-p)\nu}{(1-\nu)p}$$

 Result: Sharing information is additive in types. That is, whenever agents of types θ and φ meet, both become type θ + φ. This process is inductive over successive matching.

#### Setting for Information Percolation

**Intuition:** If the cross-sectional distribution of types is discrete, then the rate at which new agents of type  $\theta$  are created is

$$2r\int \mu_t( heta-z)\mu_t(z)\,dz=2r(\mu_t*\mu_t)( heta)a.s.$$

This sort of application of the LLN for random matching is known as the Stosszahlansatz (Boltzmann), and has been shown rigorously only in discrete time (Duffie and Sun, *AAP*, 2007).

#### Solution for Cross-Sectional Distribution of Information

The Boltzmann equation for the cross-sectional distribution μ<sub>t</sub> of types is, for λ = 2r,

$$\frac{d}{dt}\mu_t = -\lambda\,\mu_t + \lambda\,\mu_t * \mu_t. \tag{1}$$

- ▶ Standing assumption: On the event  $\{X = H\}$ , the first moment of  $\mu_0$  is strictly positive, and  $\mu_0$  has a moment generating function  $z \mapsto \int e^{z\theta} \mu_0(d\theta)$  that is finite on a neighborhood of z = 0.
- Proposition (DGM, 2008). The unique solution of (1) is the Wild sum

$$\mu_t = \sum_{n \ge 1} e^{-\lambda t} (1 - e^{-\lambda t})^{n-1} \mu_0^{*n}.$$
 (2)

#### Sketch of Proof of Wild Sum

The ODE for the characteristic function  $\varphi(\cdot, t)$  of  $\mu_t$ ,

$$\frac{\partial \varphi(\mathbf{s}, t)}{\partial t} = -\lambda \varphi(\mathbf{s}, t) + \lambda \varphi^2(\mathbf{s}, t),$$

is solved by

$$\varphi(\mathbf{s},t) = \frac{\varphi(\mathbf{s},0)}{\mathbf{e}^{\lambda t}(1-\varphi(\mathbf{s},0))+\varphi(\mathbf{s},0)}.$$

This solution can be expanded as

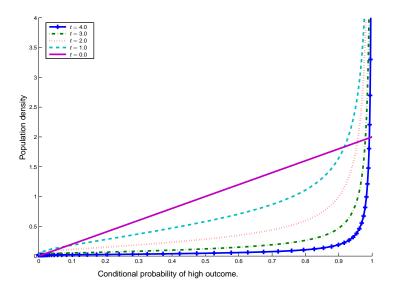
$$\varphi(\mathbf{s},t) = \sum_{n\geq 1} e^{-\lambda t} (1-e^{-\lambda t})^{n-1} \varphi^n(\mathbf{s},t),$$

which is identical to the Fourier transform of the Wild sum (2).

# Market Example

- Uninformed buyers of a contract promising X randomly select two informed sellers at intensity λ.
- A second-price auction allocates the trade to the lowest-bidding seller. (The Wallet Game.)
- In the unique symmetric equilibrium, sellers bid their posterior probabilities that X is high, revealing their types.

On the event  $\{X = H\}$ , the evolution of the cross-sectional population density of posterior probabilities of the event  $\{X = H\}$ .



#### **Convergence Rate of Population Information**

Let  $\pi_t$  be the cross-sectional distribution of posteriors at time *t*.

**Definition:** The rate of convergence of  $\pi_t$  to  $\pi_\infty$  is  $\alpha > 0$  if there are constants  $\kappa_0$  and  $\kappa_1$  such that, for any *b* in (0, 1),

$$\mathbf{e}^{-lpha t}\kappa_0 \leq |\pi_t(\mathbf{0}, b) - \pi_\infty(\mathbf{0}, b)| \leq \mathbf{e}^{-lpha t}\kappa_1.$$

**Proposition:**  $\pi_t$  converges at rate  $\lambda$  to  $\delta_0$  on the event  $\{X = L\}$  and to  $\delta_1$  on  $\{X = H\}$ .

#### Meetings of More than Two at a Time

- Groups of *m* agents are randomly matched. Because each agent is matched to others at rate *r*, the total annual quantity of attendance at meetings is λ = mr a.s.
- The associated Boltzmann equation for the type distribution is

$$\frac{d}{dt}\mu_t = -\lambda\mu_t + \lambda\,\mu_t^{*m}.$$

The solution is explicit as a Wild sum.

#### Wild Summation Solution

The unique solution of the Boltzmann equation for *m*-at-a-time matching is

$$\mu_t = \sum_{n \ge 1} a_{(m-1)(n-1)+1} e^{-\lambda t} (1 - e^{-(m-1)\lambda t})^{n-1} \mu_0^{*[(m-1)(n-1)+1]},$$

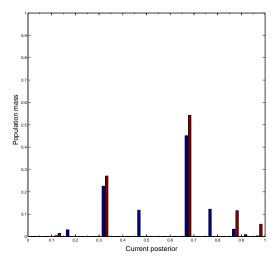
where  $a_1 = 1$  and, for n > 1,

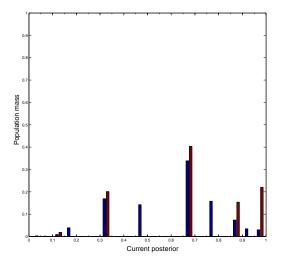
$$a_{(m-1)(n-1)+1} = \frac{1}{m-1} \left( 1 - \sum_{\substack{\{i_1, \dots, i_{(m-1)} < n \\ \sum i_k = n+m-2}} \prod_{k=1}^{m-1} a_{(m-1)(i_k-1)+1} \right).$$

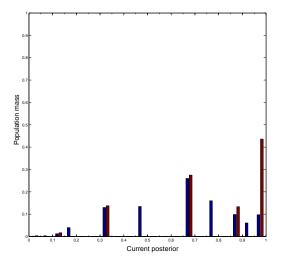
Invariance of Convergence Rate to Group Size for a Given Total Rate of Meeting Attendance

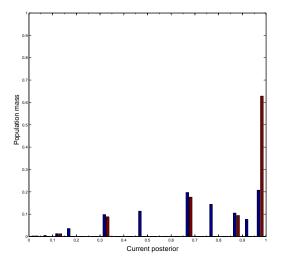
**Proposition:** For any group size *m*, the cross-sectional distribution  $\pi_t$  of posteriors converges at rate  $\lambda$ .

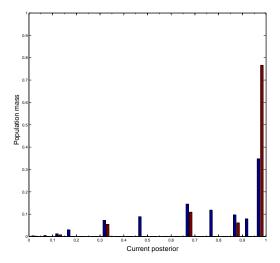
Malamud (2008) has extended this result to the case of groups of a random size.

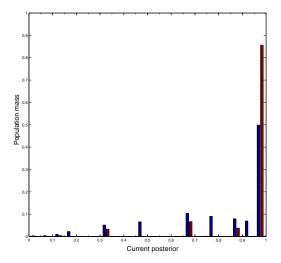


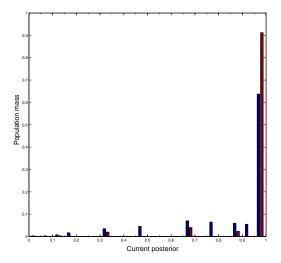












#### Equilibrium Search Dynamics With Manso and Malamud

- Signals and X are joint Gaussian, with  $corr(X, s_i) = \rho$ .
- Agents arrive at a rate proportional to the population size, and leave at exponentially distributed times, pairwise independently.
- Agents meet others at a mean rate proportional to the rate at which they choose to expend search costs.
- > At entry, agent *i* receives  $N_{i0}$  signals, *iid* across agents.
- At exit, an agent chooses an action A, with cost  $(X A)^2$ .
- ► The optimal exit action is A = E(X | F<sub>it</sub>), so the expected exit cost is the F<sub>it</sub>-conditional variance of X,

$$\sigma_{it}^2 = v(N_{it}) \equiv \frac{1-
ho^2}{1+
ho^2(N_{it}-1)}.$$

# Information Transmission

- Agent *i* has current mean  $E(X | \mathcal{F}_{it})$  and "precision"  $N_{it}$ .
- When agents *i* and *j* meet, their posterior precisions become N<sub>it</sub> + N<sub>jt</sub>. Their posterior means are given by the usual precision-weighted average of their priors.
- At constant meeting intensity λ, the cross-sectional precision distribution μ<sub>t</sub> thus behaves as before, except for the effect of arrivals and departures.

# Search Technology

- Random matching (Stosszahlanzatz).
- Given current effort c by an agent, the mean rate of matching with someone from a unit mass of agents using search effort b is cb.
- ▶ The rate of cost of search effort *c* is K(c), for  $c \in [c_L, c_H]$ .

#### Separability of Posterior Precision and Mean

*Proposition.* For any search-effort policy function  $C : \mathbb{N} \to [c_L, c_H]$ , the cross-sectional density  $f_t$  of precisions and posterior means of the agents is almost surely given by

$$f_t(n, y, \omega) = \mu_t(n) p_n(y \mid X(\omega)),$$
(3)

where  $\mu_t$  is the unique solution of the Boltzmann equation for the evolution of the cross-sectional distribution of information precision and  $p_n(\cdot | X)$  is the *X*-conditional Gaussian density of  $E(X | s_1, ..., s_n)$ , for any *n* signals  $s_1, ..., s_n$ .

### **Stationary Measure**

In a stationary setting with search policy  $\mathbf{C}$ , the precision distribution  $\mu$  solves

$$\mathbf{0} = \eta(\gamma - \mu) + \mu^{\mathbf{C}} * \mu^{\mathbf{C}} - \mu^{\mathbf{C}} \mu^{\mathbf{C}}(\mathbb{N}),$$

where

- >  $\eta$  is the mean replacement rate of agents.
- $\gamma$  is the distribution of  $N_{i0}$ .
- $\mu^{C}$  is the effort-weighted measure, with  $\mu^{C}(n) = C(n)\mu(n)$ .

# **Stationary Measure**

*Lemma.* Given any policy *C*, there is a unique measure  $\mu$  satisfying the stationary-measure equation.

This measure  $\mu$  is characterized in the paper, and under technical conditions is the pointwise limit of  $\mu_t$ , invariant to  $\mu_0$ .

# **Optimality and Equilibrium**

Given a policy *C* for other agents, agent *i* has the value function  $V(\cdot)$  defined by

$$V(N_{it}) = \operatorname{ess} \sup_{\phi} E\left(-e^{-r(\tau-t)}v(N_{i\tau}) - \int_{0}^{\tau} e^{-r(u-t)}K(\phi_{u}) du \mid \mathcal{F}_{it}\right),$$

which is characterized by the associated HJB equation.

The policy *C* is an equilibrium if  $\phi_t^* = C(N_{it})$  is optimal.

# **Trigger Policies**

A trigger policy  $C^N$ , for some integer  $N \ge 1$ , is defined by

$$\begin{array}{rcl} C_n^N & = & c_H, & n < N, \\ & = & c_L, & n \ge N. \end{array}$$

#### Information Sharing Opportunities

*Proposition.* Let  $\mu^{M}$  and  $\nu^{N}$  be the unique stationary measures corresponding to trigger policies  $C^{M}$  and  $C^{N}$  respectively. Let  $\mu^{C,N}(n) = \mu^{N}(n)C^{N}(n)$  denote the associated search-effort-weighted measure. If N > M, then  $\mu^{C,N}$  has first order stochastic dominance (FOSD) over  $\mu^{C,M}$ .

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This comparison result need not hold for non-trigger policies!

There exist cases with  $B \leq C$  but  $\mu^B$  having FOSD over  $\mu^C$ .

# Optimal Effort is Decreasing in Precision

*Proposition.* Suppose that *K* is increasing, convex, and differentiable. Then, given any population behavior  $(\mu, C)$ , the optimal search effort policy function is decreasing in precision.

*Proposition.* Suppose that  $K(c) = \kappa c$  for some scalar  $\kappa > 0$ . Then, given  $(\mu, C)$ , some a trigger policy  $C^N$  that is optimal for all agents.

# Existence of Equilibrium

*Theorem.* Suppose that  $K(c) = \kappa c$  for some scalar  $\kappa > 0$ . Then there exists a trigger policy that is an equilibrium.

### The Equilibrium Impact of a Search Subsidy

- A tax  $\tau$  is charged to each agent entering the market
- The proceeds are used to subsidize search so that the search cost is K<sub>δ</sub>(c) = (κ − δ)c.

*Proposition.* If  $C^N$  is an equilibrium with subsidy  $\delta$ , then for any  $\delta' \geq \delta$ , there exists some  $N' \geq N$  such that  $C^{N'}$  is an equilibrium with subsidy  $\delta'$ .

#### Example

- 1. For some integer N > 1,  $\gamma(0) = 1/2$ ,  $\gamma(N) = 1/2$ , and  $c_L = 0$ .
- It is possible to choose parameters so that, given market conditions (μ<sup>N</sup>, C<sup>N</sup>), agents slightly prefer policy C<sup>0</sup> over C<sup>N</sup>.
- We can choose the subsidy rate δ so that, given market conditions (μ<sup>N</sup>, C<sup>N</sup>), agents strictly prefer C<sup>N</sup> to C<sup>0</sup>.
- 4. For sufficiently large *N* all agents have strictly higher indirect utility.

### The Equilibrium Impact of Public Information

Agents are given  $M \ge 1$  additional public signals at entry.

**Proposition** If  $C^N$  is an equilibrium with M public signals, then for any  $M' \leq M$ , there exists some  $N' \geq N$  such that  $C^{N'}$  is an equilibrium with M' public signals.

We provide examples with strict dominance.

# Example

- 1. Suppose, for some integer N > 1, that  $\pi_0 = 1/2$ ,  $\pi_N = 1/2$ , and  $c_L = 0$ .
- 2. Choose parameters so that, given market conditions  $(\mu^N, C^N)$  agents are indifferent between policies  $C^N$  and  $C^0$ .
- 3. Give each agent M = 1 public signal at entry.
- 4. All agents strictly prefer  $C^0$  to  $C^N$
- 5. For sufficiently large N all agents have strictly lower indirect utility.

# Conclusion

- Model of social learning with endogenous search intensity.
- Social learning may slow down or even collapse:
  - coordination problems.
  - externality problems.
- Two policy interventions:
  - search subsidy.
  - education at entry.

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