# Information Percolation in Large Markets 

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## Information Percolation

- Markets
- Hayek (1945)
- Wolinsky (1990)
- Golosov, Lorenzoni, Tsyvinski (2008)
- Social learning
- Banerjee and Fudenberg (1995)
- Acemoglu (2008)


## Setting

From Duffie and Manso (AER 2007):

- A continuum of agents matched pairwise independently to other agents at mean rate $r$.
- Payoff relevant states: $X= \begin{cases}H & \text { with probability } \nu \\ L & \text { with probability } 1-\nu\end{cases}$
- Agent $k$ is endowed with $S_{k}=\left\{s_{1}, \ldots, s_{k_{n}}\right\},\{0,1\}$-signals that are $X$-conditionally independent, with

$$
\mathrm{P}\left(s_{i}=1 \mid X=H\right) \geq \mathrm{P}\left(s_{i}=1 \mid X=L\right) .
$$

- For almost every pair $j$ and $k$ of agents, $S_{j}$ and $S_{k}$ are disjoint.
- If $j$ and $k$ are matched, they share endowed and previously gathered signals.


## Information is Additive in Types

- For any conditional probability $p \in(0,1)$ of the event $\{X=H\}$, we define the associated information type

$$
\Theta(p)=\log \frac{(1-p) \nu}{(1-\nu) p}
$$

- Result: Sharing information is additive in types. That is, whenever agents of types $\theta$ and $\phi$ meet, both become type $\theta+\phi$. This process is inductive over successive matching.


## Setting for Information Percolation

Intuition: If the cross-sectional distribution of types is discrete, then the rate at which new agents of type $\theta$ are created is

$$
2 r \int \mu_{t}(\theta-z) \mu_{t}(z) d z=2 r\left(\mu_{t} * \mu_{t}\right)(\theta) \text { a.s. }
$$

This sort of application of the LLN for random matching is known as the Stosszahlansatz (Boltzmann), and has been shown rigorously only in discrete time (Duffie and Sun, AAP, 2007).

## Solution for Cross-Sectional Distribution of Information

- The Boltzmann equation for the cross-sectional distribution $\mu_{t}$ of types is, for $\lambda=2 r$,

$$
\begin{equation*}
\frac{d}{d t} \mu_{t}=-\lambda \mu_{t}+\lambda \mu_{t} * \mu_{t} \tag{1}
\end{equation*}
$$

- Standing assumption: On the event $\{X=H\}$, the first moment of $\mu_{0}$ is strictly positive, and $\mu_{0}$ has a moment generating function $z \mapsto \int e^{z \theta} \mu_{0}(d \theta)$ that is finite on a neighborhood of $z=0$.
- Proposition (DGM, 2008). The unique solution of (1) is the Wild sum

$$
\begin{equation*}
\mu_{t}=\sum_{n \geq 1} e^{-\lambda t}\left(1-e^{-\lambda t}\right)^{n-1} \mu_{0}^{* n} . \tag{2}
\end{equation*}
$$

## Sketch of Proof of Wild Sum

The ODE for the characteristic function $\varphi(\cdot, t)$ of $\mu_{t}$,

$$
\frac{\partial \varphi(s, t)}{\partial t}=-\lambda \varphi(s, t)+\lambda \varphi^{2}(s, t)
$$

is solved by

$$
\varphi(s, t)=\frac{\varphi(s, 0)}{e^{\lambda t}(1-\varphi(s, 0))+\varphi(s, 0)}
$$

This solution can be expanded as

$$
\varphi(s, t)=\sum_{n \geq 1} e^{-\lambda t}\left(1-e^{-\lambda t}\right)^{n-1} \varphi^{n}(s, t)
$$

which is identical to the Fourier transform of the Wild sum (2).

## Market Example

- Uninformed buyers of a contract promising $X$ randomly select two informed sellers at intensity $\lambda$.
- A second-price auction allocates the trade to the lowest-bidding seller. (The Wallet Game.)
- In the unique symmetric equilibrium, sellers bid their posterior probabilities that $X$ is high, revealing their types.

On the event $\{X=H\}$, the evolution of the cross-sectional population density of posterior probabilities of the event $\{X=H\}$.


## Convergence Rate of Population Information

Let $\pi_{t}$ be the cross-sectional distribution of posteriors at time $t$.
Definition: The rate of convergence of $\pi_{t}$ to $\pi_{\infty}$ is $\alpha>0$ if there are constants $\kappa_{0}$ and $\kappa_{1}$ such that, for any $b$ in $(0,1)$,

$$
e^{-\alpha t} \kappa_{0} \leq\left|\pi_{t}(0, b)-\pi_{\infty}(0, b)\right| \leq e^{-\alpha t} \kappa_{1} .
$$

Proposition: $\pi_{t}$ converges at rate $\lambda$ to $\delta_{0}$ on the event $\{X=L\}$ and to $\delta_{1}$ on $\{X=H\}$.

## Meetings of More than Two at a Time

- Groups of $m$ agents are randomly matched. Because each agent is matched to others at rate $r$, the total annual quantity of attendance at meetings is $\lambda=m r$ a.s.
- The associated Boltzmann equation for the type distribution is

$$
\frac{d}{d t} \mu_{t}=-\lambda \mu_{t}+\lambda \mu_{t}^{* m}
$$

- The solution is explicit as a Wild sum.


## Wild Summation Solution

The unique solution of the Boltzmann equation for $m$-at-a-time matching is

$$
\mu_{t}=\sum_{n \geq 1} a_{(m-1)(n-1)+1} e^{-\lambda t}\left(1-e^{-(m-1) \lambda t}\right)^{n-1} \mu_{0}^{*[(m-1)(n-1)+1]}
$$

where $a_{1}=1$ and, for $n>1$,

$$
a_{(m-1)(n-1)+1}=\frac{1}{m-1}\left(1-\sum_{\substack{i_{1}, \ldots, i_{(m-1)}<n \\ \sum i_{k}=n+m-2}} \prod_{k=1}^{m-1} a_{(m-1)\left(i_{k}-1\right)+1}\right) .
$$

## Invariance of Convergence Rate to Group Size for a Given Total Rate of Meeting Attendance

Proposition: For any group size $m$, the cross-sectional distribution $\pi_{t}$ of posteriors converges at rate $\lambda$.

Malamud (2008) has extended this result to the case of groups of a random size.

## Groups of 2 (blue) versus Groups of 3 (red)



## Groups of 2 (blue) versus Groups of 3 (red)



## Groups of 2 (blue) versus Groups of 3 (red)



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## Equilibrium Search Dynamics

## With Manso and Malamud

- Signals and $X$ are joint Gaussian, with $\operatorname{corr}\left(X, s_{i}\right)=\rho$.
- Agents arrive at a rate proportional to the population size, and leave at exponentially distributed times, pairwise independently.
- Agents meet others at a mean rate proportional to the rate at which they choose to expend search costs.
- At entry, agent $i$ receives $N_{i 0}$ signals, iid across agents.
- At exit, an agent chooses an action $A$, with cost $(X-A)^{2}$.
- The optimal exit action is $A=E\left(X \mid \mathcal{F}_{i t}\right)$, so the expected exit cost is the $\mathcal{F}_{\text {it }}$-conditional variance of $X$,

$$
\sigma_{i t}^{2}=v\left(N_{i t}\right) \equiv \frac{1-\rho^{2}}{1+\rho^{2}\left(N_{i t}-1\right)}
$$

## Information Transmission

- Agent $i$ has current mean $E\left(X \mid \mathcal{F}_{i t}\right)$ and "precision" $N_{i t}$.
- When agents $i$ and $j$ meet, their posterior precisions become $N_{i t}+N_{j t}$. Their posterior means are given by the usual precision-weighted average of their priors.
- At constant meeting intensity $\lambda$, the cross-sectional precision distribution $\mu_{t}$ thus behaves as before, except for the effect of arrivals and departures.


## Search Technology

- Random matching (Stosszahlanzatz).
- Given current effort $c$ by an agent, the mean rate of matching with someone from a unit mass of agents using search effort $b$ is cb.
- The rate of cost of search effort $c$ is $K(c)$, for $c \in\left[c_{L}, c_{H}\right]$.


## Separability of Posterior Precision and Mean

Proposition. For any search-effort policy function $C: \mathbb{N} \rightarrow\left[c_{L}, c_{H}\right]$, the cross-sectional density $f_{t}$ of precisions and posterior means of the agents is almost surely given by

$$
\begin{equation*}
f_{t}(n, y, \omega)=\mu_{t}(n) p_{n}(y \mid X(\omega)) \tag{3}
\end{equation*}
$$

where $\mu_{t}$ is the unique solution of the Boltzmann equation for the evolution of the cross-sectional distribution of information precision and $p_{n}(\cdot \mid X)$ is the $X$-conditional Gaussian density of $E\left(X \mid s_{1}, \ldots, s_{n}\right)$, for any $n$ signals $s_{1}, \ldots, s_{n}$.

## Stationary Measure

In a stationary setting with search policy $C$, the precision distribution $\mu$ solves

$$
0=\eta(\gamma-\mu)+\mu^{C} * \mu^{C}-\mu^{C} \mu^{C}(\mathbb{N}),
$$

where

- $\eta$ is the mean replacement rate of agents.
- $\gamma$ is the distribution of $N_{i 0}$.
- $\mu^{C}$ is the effort-weighted measure, with $\mu^{C}(n)=C(n) \mu(n)$.


## Stationary Measure

Lemma. Given any policy $C$, there is a unique measure $\mu$ satisfying the stationary-measure equation.

This measure $\mu$ is characterized in the paper, and under technical conditions is the pointwise limit of $\mu_{t}$, invariant to $\mu_{0}$.

## Optimality and Equilibrium

Given a policy $C$ for other agents, agent $i$ has the value function $V(\cdot)$ defined by

$$
V\left(N_{i t}\right)=\operatorname{ess} \sup _{\phi} E\left(-e^{-r(\tau-t)} v\left(N_{i \tau}\right)-\int_{0}^{\tau} e^{-r(u-t)} K\left(\phi_{u}\right) d u \mid \mathcal{F}_{i t}\right),
$$

which is characterized by the associated HJB equation.
The policy $C$ is an equilibrium if $\phi_{t}^{*}=C\left(N_{i t}\right)$ is optimal.

## Trigger Policies

A trigger policy $C^{N}$, for some integer $N \geq 1$, is defined by

$$
\begin{aligned}
C_{n}^{N} & =c_{H}, \quad n<N, \\
& =c_{L}, \quad n \geq N .
\end{aligned}
$$

## Information Sharing Opportunities

Proposition. Let $\mu^{M}$ and $\nu^{N}$ be the unique stationary measures corresponding to trigger policies $C^{M}$ and $C^{N}$ respectively. Let $\mu^{C, N}(n)=\mu^{N}(n) C^{N}(n)$ denote the associated search-effort-weighted measure. If $N>M$, then $\mu^{C, N}$ has first order stochastic dominance (FOSD) over $\mu^{C, M}$.

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This comparison result need not hold for non-trigger policies!
There exist cases with $B \leq C$ but $\mu^{B}$ having FOSD over $\mu^{C}$.

## Optimal Effort is Decreasing in Precision

Proposition. Suppose that $K$ is increasing, convex, and differentiable. Then, given any population behavior ( $\mu, \boldsymbol{C}$ ), the optimal search effort policy function is decreasing in precision.

Proposition. Suppose that $K(c)=\kappa c$ for some scalar $\kappa>0$. Then, given $(\mu, C)$, some a trigger policy $C^{N}$ that is optimal for all agents.

## Existence of Equilibrium

Theorem. Suppose that $K(c)=\kappa c$ for some scalar $\kappa>0$. Then there exists a trigger policy that is an equilibrium.

## The Equilibrium Impact of a Search Subsidy

- A tax $\tau$ is charged to each agent entering the market
- The proceeds are used to subsidize search so that the search cost is $K_{\delta}(c)=(\kappa-\delta) c$.

Proposition. If $C^{N}$ is an equilibrium with subsidy $\delta$, then for any $\delta^{\prime} \geq \delta$, there exists some $N^{\prime} \geq N$ such that $C^{N^{\prime}}$ is an equilibrium with subsidy $\delta^{\prime}$.

## Example

1. For some integer $N>1, \gamma(0)=1 / 2, \gamma(N)=1 / 2$, and $c_{L}=0$.
2. It is possible to choose parameters so that, given market conditions ( $\mu^{N}, C^{N}$ ), agents slightly prefer policy $C^{0}$ over $C^{N}$.
3. We can choose the subsidy rate $\delta$ so that, given market conditions ( $\mu^{N}, C^{N}$ ), agents strictly prefer $C^{N}$ to $C^{0}$.
4. For sufficiently large $N$ all agents have strictly higher indirect utility.

## The Equilibrium Impact of Public Information

Agents are given $M \geq 1$ additional public signals at entry.
Proposition If $C^{N}$ is an equilibrium with $M$ public signals, then for any $M^{\prime} \leq M$, there exists some $N^{\prime} \geq N$ such that $C^{N^{\prime}}$ is an equilibrium with $M^{\prime}$ public signals.

We provide examples with strict dominance.

## Example

1. Suppose, for some integer $N>1$, that $\pi_{0}=1 / 2, \pi_{N}=1 / 2$, and $c_{L}=0$.
2. Choose parameters so that, given market conditions $\left(\mu^{N}, C^{N}\right)$ agents are indifferent between policies $C^{N}$ and $C^{0}$.
3. Give each agent $M=1$ public signal at entry.
4. All agents strictly prefer $C^{0}$ to $C^{N}$
5. For sufficiently large $N$ all agents have strictly lower indirect utility.

## Conclusion

- Model of social learning with endogenous search intensity.
- Social learning may slow down or even collapse:
- coordination problems.
- externality problems.
- Two policy interventions:
- search subsidy.
- education at entry.


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